



JXM-IO-E30

Version update from V2.24.0.00 to V2.27.0.00

Revision 1.14

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Table of contents

1	Changes to 2.27.0.00	4
2	Changes to 2.23.0.00	5
3	Changes to 2.22.0.00	6
4	Changes to 2.20.0.00	7
5	Changes to 2.17.0.00	8
6	Changes to 2.16.0.00	9
7	Changes to 2.15.0.00	10
8	Changes to 2.13.0.00	11
9	Changes to 2.12.0.00	12
10	Changes to 2.11.0.00	13
11	Changes to 2.09.0.00	15
12	Changes to 2.07.0.00	16
13	Changes to 2.06.0.00	17
14	Changes to 2.04.0.00	18
15	Changes to 2.03.0.00	19
16	Changes to 2.02.0.00	20
17	Changes to 2.00.0.00	21

1 Changes to 2.27.0.00

Overview

Version 2.27.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
Assigning values with incorrect data type will now be rejected by the OS. This change affects all objects.	✓		
SDO abort codes have been revised			✓
0x2000 : sub0 returns last subindex sub103			✓
0x4556 : sub3 (Baud rate) data type changed from u16 to u8			✓
0x2100...0x2107 : sub63 (MIN_DEVIATION) auf 10 erhöht.	✓		
0x210C...0x2119 : sub65 (OPEN_CIRCUIT_DETECTION) data type changed from u8 to u16			✓
0x2108...0x210B : sub59, sub62, sub68 (TIMEOUT_TIME, RESOLUTION & GATE_TIME) now send SDO abort DATATRANSFERSTORESTAT on forbidden access. (f.ex. when configured as digital input)	✓		
0x210C...0x2115 : sub30, sub31 (O_DIGITAL, O_DUTY_CYCLE) now send SDO abort DATATRANSFERSTORESTAT on forbidden access. (f.ex. when configured as PWM output)	✓		
0x210C...0x210F : sub32 (O_HCURRENT) now send SDO abort DATATRANSFERSTORESTAT on forbidden access. (f.ex. when configured as digital input)	✓		
0x210C...0x210F : I_DUTY_CYCLE removed, since it's not supported by hardware.			✓
0x1010...0x1011 : SAVE/LOAD now returns 1 on default.	✓		
0x6411...0x6412 : sub indexes 1...10 may not be set during PreOP. The returned code 0x00000001 was no valid SDO abort code.			✓
Heartbeat monitoring behaviour was improved (Timing, error handling...)	✓		
Removed objects: 0x100B, 0x1002, 0x1029, 0x1201, 0x1202, 0x1203	✓		
0x2108...0x210B : rotary encoder : I_DIRECTION will now reach 0 (stopped) after the full TIMEOUT_TIME has passed.			✓

2 Changes to 2.23.0.00

Overview
Version 2.23.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
Fix: Supply voltage fluctuations could indicate repeated partial resets. As a result the I2C bus malfunctioned, which also affected EEPROM communication. Error pattern: The node is reacting normally, but the LED matrix won't light up.			✓

3 Changes to 2.22.0.00

Overview

Version 2.22.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
Fix: A downgrade to OS versions lesser than 2.17.0.00 is now possible again.			✓
Fix: JXM-IO-EX30: LED-Matrix: Status LEDs of AI ports, when configured as AI_VOLTAGE, now are switched on correctly.			✓
Fix: JXM-IO-EX30: LED-Matrix: Status LEDs of AI ports, when configured as AI_CURRENT, now are reset after an OVERCURRENT event.			✓
Fix: JXM-IO-EX30: DS401: Reading of sub indexes of object 0x6411, is now successful.			✓
Fix: JXM-IO-EX30: DS401: When customizing the default configuration of RPDO1, writing O_DIGITAL in the target output is now successful.			✓
Fix: JXM-IO-EX30: DS401: According to default configuration, TPDO1 now transmits I_DIGITAL values of DI ports.			✓
New: JXM-IO-EX30: DS401: PDOs now are automatically active when going OPERATIONAL.	✓		
Fix: PDO Subindex 2 now returns the configured transmit type CANOPEN_ASYNPDO (0xFE).			✓

4 Changes to 2.20.0.00

Overview
Version 2.20.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
The LED matrix now also works on a JXM-IO-EX30.			✓
JXM-IO-EX30 extended by DS401 functionality.		✓	
Fix: TPDO now send 0 when calibration and scaling lead to negative values.			✓

5 Changes to 2.17.0.00

Overview

Version 2.17.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
The green LED now also works on a JXM-IO-EX30.			✓

6 Changes to 2.16.0.00

Overview Version
2.16.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
Fix direction of I_COUNTER and I_DIRECTION when digital inputs are configured as rotary encoder and RESOLUTION is set to 2.			✓
Fix I_PERIODIC_TIME previously was updated after GATE_TIME. Now the calculations triggered, when a flank is counted during frequency measuring.			✓
Fix the maximum value of DITHER_FREQUENCY to 8000.			✓
Fix the update time of TPDO4. Before, when four TPDO were configured, TPDO4 experienced delays up to 2s.			✓

7 Changes to 2.15.0.00

Overview

Version 2.15.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
Fix broken OS update when Node-ID is changed by Config pin and or system parameter.			✓
Fix CAN settings if corrupted in EEPROM.			✓
Fix minimal accepted value of GATE_TIME from 1000ms to 10ms.			✓

8 Changes to 2.13.0.00

Overview The following table gives an overview of newly added or enhanced features and fixed software bugs:
Version 2.13.0.00

Description	New	Enhanced	Fixed
The Node-ID of variants JXM-IO-EX30 and JXM-IO-EW30 does no longer depend on whether VBAT_PWR is connected.			✓

9 Changes to 2.12.0.00

Overview

Version 2.12.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
<p>IDX 0x2108...0x210B: fix immediate emergency message when configuring DI as frequency input. Now emergency timeout message will only be sent after the timeout_time has been exceeded.</p> <p>Also, change maximum timeout_time from 1000ms to 2^16ms.</p>			✓
<p>IDX 0x2108...0x210B: Use of AB track sensor. (requires the combination of two ports using one Interface)</p> <p>New subindexes: I_DIRECTION (22), ENC_PNP (26) and RESOLUTION (68). Uses subindexes: I_COUNTER (17) and TIMEOUT_TIME (59).</p> <p>Subindex 26: Interface. Subindex 17: Input value tick count (overflow at 0 -1 and UINT32_MAX +1). Subindex 22: Input value direction (0=stop, 1=forward, 2=backward). Subindex 68: Parameter resolution in ppr (0=1/4, 1=1/2, 2=full) Subindex 59: Parameter period after which the direction signals stop.</p>	✓		
<p>IDX 1016: Heartbeat monitoring may trigger switch to NMT_STOPPED when timeout occurred.</p> <p>Subindex 0 number of monitorable Node-IDs. (RO) Subindex 1...4 set the Node-ID to be monitored as well as the timeout time.</p>	✓		
<p>The Node-ID of variants JXM-IO-EX30 and JXM-IO-EW30 does no longer depend on whether or not VBAT_PWR is connected.</p>			✓

10 Changes to 2.11.0.00

Overview Version 2.11.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
IDX 0x210C...0x2119: Additional feature. When set to HSxD, the functionality can be read back in I_DIGITAL.		✓	
IDX 0x210C...0x2119: change default of OPENCIRCUIT_DETECTION from 2=PERMANENT to 1=STARTUP. Open circuit will now only be detected during startup.	✓		
IDX 0x210C...0x2115: Fixed PWM frequency from minimal 100Hz to minimal 5 Hz.			✓
IDX 0x2100...0x2107: fix faulty check when voltage EMCY-messages are re/set.			✓
IDX all: added internal Watchdog to reboot system in case main thread execution is halted/blocked.	✓		
Fixed bug in TPDOs where the configured INHIBIT_TIME for certain values was additional 10ms longer.			✓
IDX 0x2000, SubIDX 10 to 12: Added 100mV Hysteresis. When SPWR is monitored by TPDO this prevents the TPDO from constantly triggering.	✓		
Pdated CAN driver	✓		

11 Changes to 2.09.0.00

Overview
Version 2.09.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
IDX 0x210C...0x2119: A bug when resetting set points of outputs is now fixed. When changing to state OPERATIONAL, set points are now reset to 0 in all cases.			✓
IDX 0x210C...0x2119: MIN_CURRENT (SubIndex 64, uint16, r/w) and OpenLoadDetection (automatically executed at system start) can now be turned off. This is controlled via the new SubIndex 65, OPENCIRCUIT_DETECTION. OPENCIRCUIT_DETECTION accepts the values 0=all off, 1=OpenLoadDetection is executed once during startup, 2=OpenLoadDetection and MIN_CURRENT are both active.	✓	✓	

12 Changes to 2.07.0.00

Overview

Version 2.07.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
IDX 0x210C...0x2119: Set point values for Output ports (SubIndexe 30, 31 und 32, uint8, uint16 und uint16, r/w) now can only be set in state OPERATIONAL. In PreOPERATIONAL and when entering state OPERATIONAL set point values will be set to 0 always. This way, when entering state OPERATIONAL, sudden, uncontrolled actions of connected actors are prevented.	✓		

13 Changes to 2.06.0.00

Overview
Version 2.06.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
IDX 0x210C...0x2119: Output ports provide a cable break detection (SubIndex 64, uint16, r/w). Minimal current on default is 200mA for HS3CC and HS3C, else it's 500mA. When falling below the minimal current, an EMCY-message for the respective port is sent. Also the port state will read OPEN_CIRCUIT. Only available in state OPERATIONAL.	✓		
IDX 0x2000: Reduction of bus load, when diag indices 1 and/or 12 are being included in an TPDO.		✓	

14 Changes to 2.04.0.00

Overview
Version 2.04.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
If an output is configured to DI_NPN or DI_PNP, a pull up resistor is switched on or off for the corresponding group. Now this only depends on the latest configured interface.			✓
IDX 0x1010: Changes of the HeartbeatTime will now be saved.		✓	
IDX 0x6000: Display of digital values was broken in revision 2.03.0.00. This has been fixed.			✓
IDX 0x4556: When saving unchanged system parameter, the CRC was altered. This has been fixed.			✓
CanOpen stack: has been enhanced. The DLC of PDOs now no more exceeds the number of bytes mapped.		✓	
IDX 0x210C...0x210F: If Setpoint O_HCURRENT was set to 0, the output didn't reach 0A. Instead the output stayed within the tolerance level. This has been fixed.			✓
Output ports are now only active in state OPERATIONAL.	✓		
Analogue input values now have noise cancelling. The default value is 1, meaning, no noise cancellation. You can configure this in subindex 63.	✓		

15 Changes to 2.03.0.00

Overview
Version 2.03.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
fixed: only on hardware revision 01.00 devices: current regulation function on PWMi_H3 was not functional. This software version does not affect devices with hardware revision 02.00 or above			✓

16 Changes to 2.02.0.00

Overview

Version 2.02.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
fixed: interrupting OS update resulted in an unusable device, that could only be repaired by the manufacturer.			✓

17 Changes to 2.00.0.00

Overview
Version 2.00.0.00

The following table gives an overview of newly added or enhanced features and fixed software bugs:

Description	New	Enhanced	Fixed
implemented: AI_x analog input may be used as digital input by assigning interface type DI_PNP	✓		
implemented: Save / restore of configuration data using IDX 0x1010 / 0x1011	✓		
implemented: DI_P_1 useable as additional NPN input by assigning interface type DI_PNP (requires HW Rev. 02.00) Interface type FI_NPN may now be assigned too	✓		
implemented: reading of VBAT_ECU using diag object 0x2000/13 fixed: Node-ID now is calculated based on VBAT_ECU instead of VBAT_PWR (requires HW Rev. 02.00)	✓		✓
implemented: bitwise PDO mapping	✓		
fixed: Firmware updates may now be done using other baud rates than 250Kbit			✓
fixed: erroneous activation of PWMi_HS_3 after reset in firmware as well as in bootloader			✓
fixed: reading of status of SENSOR_SUPPLY was not implemented for outputs configured as digital inputs (DI_PNP)			✓
implemented: changed to newer version of CanOpenStack, improves over all stability	✓		
implemented: configurable Base/Node-ID in IDX 0x4556 (System parameter)	✓		
improved speed of current control by changes in default values			✓
implemented: P parameter of current control now independent of battery voltage	✓		
fixed: freeze (buffer overflow) due to high load of PDO-TX			✓
fixed: reading of SPWR_3 voltage returned SPWR_2 voltage in diag object (IDX 0x02000)			✓
fixed: parameter FILTER_DEEP didn't work for all outputs of DO_H3 and PWM_H7			✓
implemented: generation of errors OVERCURRENT and OVERVOLTAGE in analog inputs AI			✓
implemented: full functionality in regard of operating manual Version 1.20.2 (issued 2018-10-09)			
fixed: diag objects may now be mapped and transmitted via PDO			✓

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